

Patrick Benito Eberhard

Email: patrick@fictionalemail.com | **Phone:** +1 (650) 000-0000
LinkedIn: linkedin.com/in/patrick-benito | **GitHub:** github.com/patrick-benito

Education

Skyline University, MSc in Robotics and Intelligent Systems Techburg, Techland 2023 — 2025

- Relevant courses: Autonomous Vehicle Navigation, Advanced Robot Control, AI for Robotics.

Global Tech Institute, Visiting Student Innovate City, Phosphorus Valley Feb. — July 2023

- Relevant courses: Machine Learning for Robotics, Real-Time Systems, Sensor Fusion for Robotics.

Mountainview University, BSc in Mechatronics Engineering Techburg, Techland 2019 — 2022

- Graduated with Honors

Experience

Techland Institute of Robotics, Visiting Researcher Techburg, Techland Feb. — Aug. 2025

- Conducting research on the application of Quantum Neural Networks in autonomous robotic systems under Prof. Isaac Winters, focusing on enhancing real-time decision-making in dynamic environments.
- Developing advanced control algorithms for flexible robotic arms using reinforcement learning techniques, surpassing current model accuracy benchmarks.
- Designing a cross-disciplinary simulation framework integrating augmented reality for robotics training and policy evaluation, contributing to the open-source project *TechSim/robotics-sim*.

FutureTech Robotics, Robotics Engineer Intern Innovative City, Phosphorus Valley June — Dec. 2024

- Led the design and deployment of an autonomous warehouse management system, using advanced robot coordination protocols, cutting operational inefficiencies by 80%.
- Created a decentralized multi-robot communication platform, improving task allocation efficiency in high-density robotic environments (*Go, Docker*).
- Enhanced sensor calibration systems, developing precision control algorithms for robotic arms in dynamic settings (*Python, TensorFlow*).

Innovative Research Center, Techland University, Research Assistant Techburg, Techland Jan. — Dec. 2024

- Created an innovative motion planning strategy for drone swarms with non-linear dynamics, optimizing operational efficiency in unpredictable weather conditions (*ROS, Python*).
- Co-authored research on adaptive disturbance suppression techniques for robotic arms, published in Techland Robotics Journal.
- Implemented a machine learning-based control system for autonomous cars using real-time traffic data (*TensorFlow, OpenCV*).

AeroTech Innovations, Software Engineer Techland, Techland Sept. 2021 — Dec. 2022

- Co-designed and tested a suborbital rocket with an electric propulsion system, reducing environmental impact in space exploration. Demonstrated the project at the *TechWorld Expo*.
- Led the software development for the rocket's avionics system, ensuring stability and safety during flight (*Matlab, Python, C++, STM32, RaspberryPi*).
- Developed a data analysis tool for monitoring rocket telemetry, enabling early detection of propulsion issues in real-time (*Node.js, Grafana, InfluxDB, Nginx*).
- Participated in rocket test flights as a technical lead, ensuring compliance with safety standards and optimizing flight performance.

Publications

Quantum Neural Networks for Autonomous Robotic Systems: A Reinforcement Learning Approach, L. Winters, J. P. Evans, M. T. Green, R. J. Harris, E. M. Ortega [Under review](#)

Optimized Control of Soft Robotic Arms: Neural Networks in Model Predictive Control, K. Reeve, S. Zhang, A. T. Holden, R. C. Harris, M. A. Daniels [ICRA 2025](#)

Honours and Awards

Best Paper Award in Robotics and Control, FutureTech Conference Nov. 2024

Academic Excellence Award, Techland University Sept. 2023 — 2025

Outstanding Undergraduate Achievement Award, Techland Institute of Engineering Sept. 2021 and Sept. 2023

Best Engineering Project Award, Innovative City Expo June 2022

Techland National Innovation Award, Techland Innovation Foundation 2018–2020

Skills and Interests

Languages: English (Fluent), Techlandish (Native), Spanish (Intermediate), French (Basic)

Interests: Suborbital rocketry, deep-sea exploration, artificial intelligence, autonomous robotics, quantum computing.

Programming Languages: Python, C++, Go, Rust, Matlab, SQL, TensorFlow, PyTorch, ROS 2, Unity, Git, Linux, Kubernetes.